

**Device** ..... 1  
    Motion ..... 1  
    Speed Setup ..... 1

# Device

× Master

## Motion

- ' Servo-OFF '
  - 'Break Type Motor'가 , Servo-OFF 가 .
- 'Emergency Stop ' Servo-OFF '
  - Emergency Stop , Servo-OFF 가 .

## Speed Setup

- ' IDE '
  - IDE
    - IDE , .
- ' ratio 가 '
  - ratio : 10
    - WorkSpeed 가 1200 , 가 12000 .
    - 가 .
- 가
- - **Speed Apply** , .
    - , .
    - , .

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