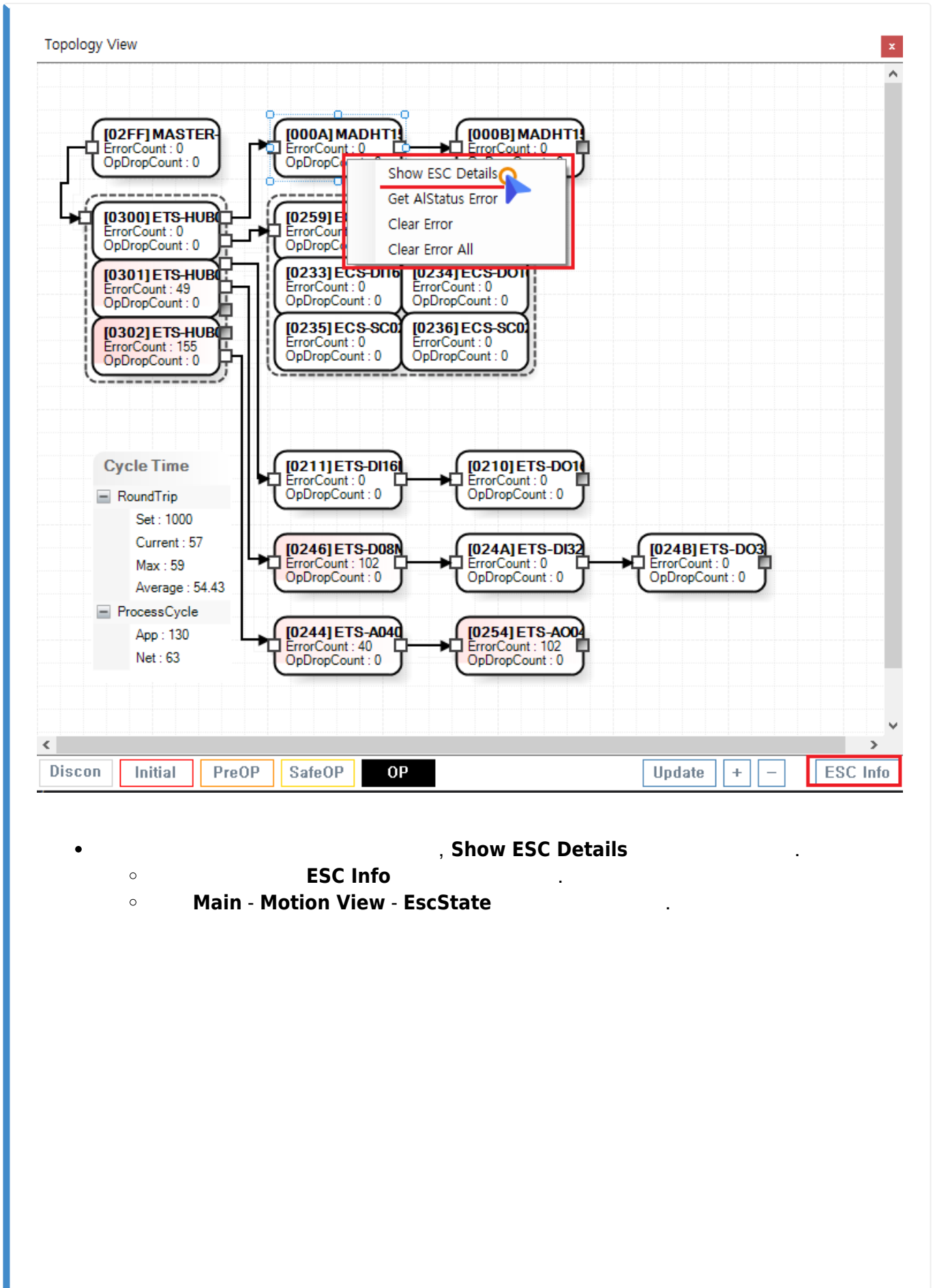


ESC State 1
Details 2

ESC State

× EtherCAT



- **Show ESC Details**
 - **ESC Info**
 - **Main - Motion View - EscState**

The screenshot displays two windows: 'Topology View' and 'ESC State'. The 'Topology View' shows a network diagram with nodes like [02FF] MASTER, [000A] MADHT1, and various ETS and ECS nodes. The 'ESC State' window shows the 'MADHT1505BA1' node with an 'EtherCAT Processor' and four ports (Port 0, Port 1, Port 2, Port 3). Each port has a table of error counts: 'Link', 'Open', 'Comm', 'Lost Link', 'Invalid Frame', 'Rx Error', and 'Forwarded Rx Error'. The 'Error' counter in the processor is 0. A status bar at the bottom shows 'Discon', 'Initial', 'PreOP', 'SafeOP', 'OP', and 'ESC Info'.

Details

This screenshot is similar to the one above but includes detailed annotations in yellow text. It explains the 'Selected Node Name' (MADHT1505BA1), navigation buttons ('Click to show the previous ESC', 'Click to show the next ESC'), and the 'Register Type' (IPcore). It also points to the 'Error Reset' button and the 'Click to Clear Errors' button. The annotations define the 'ECAT Processing Unit Error Counter' and the 'Port Number'. A legend explains the 'Comm' status: 'Comm : Communication on Port (No Stable / Establish)' and 'Link : Physical Link on Port (No Link / Link Detected)'. The 'OP' status is highlighted in the bottom bar.

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