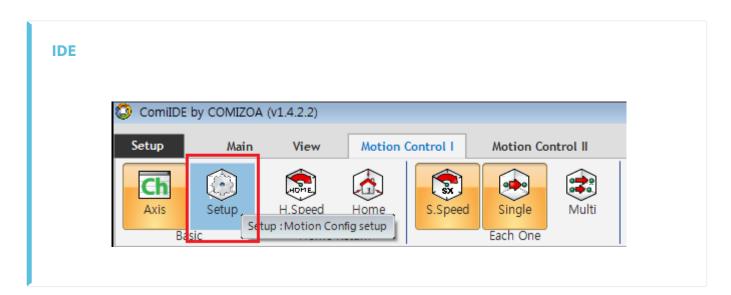
IDE .....

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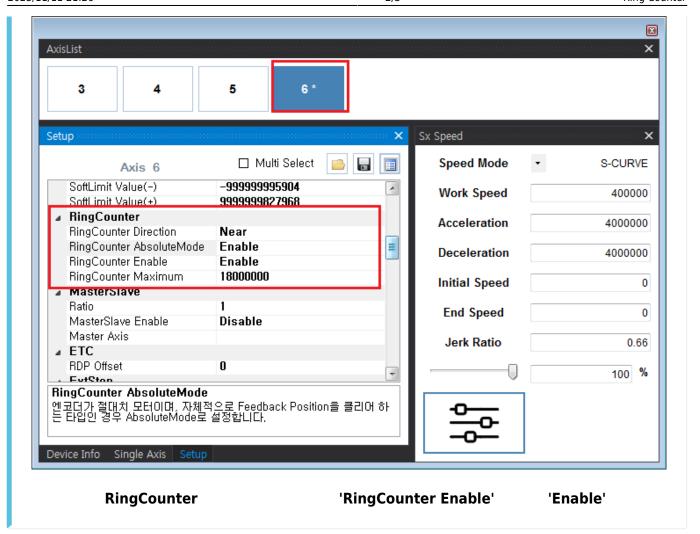
## **Ring Counter**

× (Ring Counter)

```
・ 0 ,0 .
・ 360,000 1 RingCounter 360,000 .
っ 360,000 0 .
```



• Motion Control I Setup



• RingCounter Direction :

• Negative : (-)

• Positive : (+)

○ Near: 가

∘ Far:

• RingCounter AbsoulteMode : Motor Type

Enable : Motor Type Absoulte

o Disable : Motor Type Incremental

• RingCounter Enable

∘ Enable : RingCounter

Disable : RingCounter

Absolute Type , Position Maximum

Maximum

• RingCounter Maximum : RingCounter Range

0 ~ Maximum - 1

■ Maximum 10,000 0 ~ 9999

 $\circ$  UnitDistance , 0 ~ (Maximum - 1) / UnitDistance

■ Maximum 10,000 , UnitDistance가 200 , 0 ~ 49.995 .

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