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# Gantry

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- Gantry Command Position, Feedback Position
- 가 1000 1000 100 1100 ,

- Position Monitor “C.Position.PreCorrection”, “F.Position.PreCorrection”
  - “C.Position.PreCorrection” Command Position
  - “F.Position.PreCorrection” Feedback Position
  - Position Count “C.Count.PreCorrection”, “F.Count.PreCorrection”

| Position Monitor |             |   |          |        |
|------------------|-------------|---|----------|--------|
| Reset            | C. Position | <input checked="" type="checkbox"/> C.Position<br><input type="checkbox"/> F.Position<br><input type="checkbox"/> C.Count<br><input type="checkbox"/> F.Count<br><input checked="" type="checkbox"/> C.Speed<br><input checked="" type="checkbox"/> F.Speed<br><input checked="" type="checkbox"/> Torque<br><input type="checkbox"/> C.Position.Motor<br><input type="checkbox"/> F.Position.Motor<br><input type="checkbox"/> C.Position.PreCorrection<br><input type="checkbox"/> F.Position.PreCorrection<br><input type="checkbox"/> C.Count.Motor<br><input type="checkbox"/> F.Count.Motor<br><input type="checkbox"/> C.Count.PreCorrection<br><input type="checkbox"/> F.Count.PreCorrection | F. Speed | Torque |
| Axis 0           | 200 000     |   | 0        | - 8.70 |
| Axis 1           | 200 000     |   | 0        | 8.90   |
| Axis 2           | 0           |   | - 2      | 0.00   |

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| Reset  | C.Position | F.Position | C.Speed | F.Speed | Torque | C.Pos.Pre Corr | F.Pos.PreC orr |
|--------|------------|------------|---------|---------|--------|----------------|----------------|
| Axis 0 | 100 000    | 100 000    | 0       | - 7     | - 8.30 | 100 000        | 100 000        |
| Axis 1 | 100 000    | 100 000    | 0       | 0       | 3.20   | 99 900         | 99 900         |
| Axis 2 | 0          | - 2        | 0       | 2       | 0.00   | 0              | - 2            |

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