

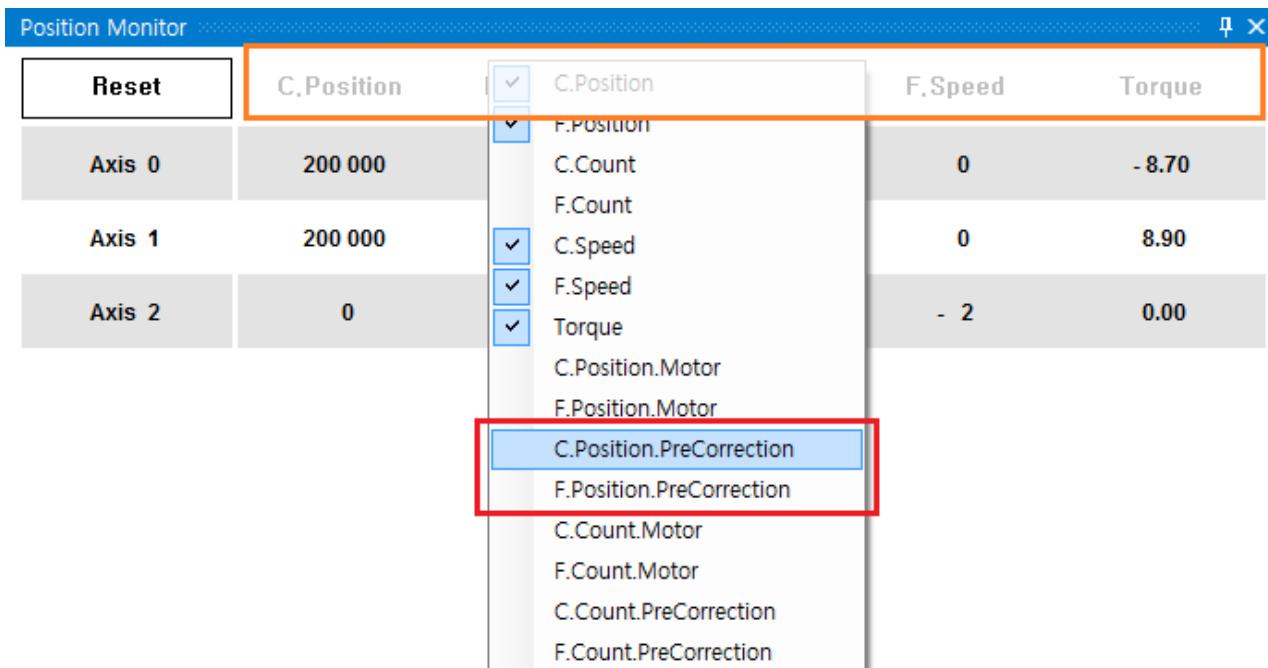
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Gantry

x Gantry

- Gantry Command Position, Feedback Position
 - $\begin{array}{c} \uparrow 1000 \\ 1100 \end{array}$ 100

- Position Monitor
 - “F.Position.PreCorrection”
 - “C.Position.PreCorrection”
 - “F.Position.PreCorrection”
 - Position Count
 - “F.Count.PreCorrection”
 - “C.Position.PreCorrection”, Command Position
 - “F.Position.PreCorrection”, Feedback Position
 - “C.Count.PreCorrection”, “C.Count.PreCorrection”,



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Position Monitor						
	C.Position	F.Position	C.Speed	F.Speed	Torque	C.Pos.PreCorr F.Pos.PreCorr
Axis 0	100 000	100 000	0	- 7	- 8.30	100 000 100 000
Axis 1	100 000	100 000	0	0	3.20	99 900 99 900
Axis 2	0	- 2	0	2	0.00	0 - 2

comizoa, , ide, ethercat, gantry, , ,

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<http://comizoa.com/info/> - -

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