

.....	1
.....	1
.....	1

×

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- 가

- Initial speed → WorkSpeed → End Speed<sup>1)</sup>

Initial speed → WorkSpeed → End Speed
- Initial Speed, End Speed0
- 0000가

- Initial Speed, End Speed, Acceleration, Deceleration<sup>2)</sup>

1)

End SpeedEnd Speed = Initial Speed

2)

가500010000가1End Speed, 2

Initial Speed5000, 1Decel0

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