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Zero Vibration

x EtherCAT Driver

Info

- Input Shaping : 가

ZeroVibration	ZeroVibration

API

ecmSxCfg_SetZVISParam :

* int ecmSxCfg_SetZVISParam (int NetID, int Axis, double NaturalFrequency, double DampingRatio, int ZVISMode, ref int ErrCode);

- NetID : Network
- Axis :
- NaturalFrequency : (1.0hz ~)
- DampingRatio : (default : 0)
- ZVISMode : (1 ~ 2)
 - 가
- ErrCode : , NULL
- Return Value : CmdIdx ¹⁾

ecmSxCfg_SetZVISEnable :

* int ecmSxCfg_SetZVISEnable(int NetID, int Axis, bool isEnabled, ref int ErrCode)

- NetID : Network
- Axis :
- isEnabled : (true / false)
- ErrCode : , NULL

- Return Value : CmdIdx ²⁾

C#

```
// int ecmSxCfg_SetZVISParam(int NetID, int Axis, double
NaturalFrequency, double DampingRatio, int ZVISMMode, ref int ErrCode)
// int ecmSxCfg_SetZVISEnable(int NetID, int Axis, bool isEnabled, ref
int ErrCode)

//          : 5.5 /          : 0 / Mode : 2
ecmSxCfg_SetZVISParam(netID, axisID, 5.5, 0, 2, ref errorCode);
if (errorCode != 0)
{
    //
}

//
ecmSxCfg_SetZVISEnable(netID, axisID, true, ref errorCode);
if (errorCode != 0)
{
    //
}
```

1) 2)

ComiECAT SDK

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