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Zero Vibration

× EtherCAT Driver

Info

- Input Shaping : 가

ZeroVibration	ZeroVibration

API

ecmSxCfg_SetZVISParam :

* int ecmSxCfg_SetZVISParam (int NetID, int Axis, double NaturalFrequency, double DampingRatio, int ZVISMode, ref int ErrCode);

- NetID : Network
- Axis :
- NaturalFrequency : (1.0hz ~)
- DampingRatio : (default : 0)
- ZVISMode : (1 ~ 2)
 - 가
- ErrCode : , NULL
- Return Value : CmdIdx ¹⁾

ecmSxCfg_SetZVISEnable :

* int ecmSxCfg_SetZVISEnable(int NetID, int Axis, bool isEnabled, ref int ErrCode)

- NetID : Network
- Axis :
- isEnabled : (true / false)
- ErrCode : , NULL

- Return Value : CmdIdx ²⁾

C#

```
private void SetZeroVibration(int axisID)
{
    // int ecmSxCfg_SetZVISParam(int NetID, int Axis, double
    NaturalFrequency, double DampingRatio, int ZVISMode, ref int ErrCode)
    // int ecmSxCfg_SetZVISEnable(int NetID, int Axis, bool isEnabled,
    ref int ErrCode)

    //      : 5.5 /      : 0 / Mode : 2
    ecmSxCfg_SetZVISParam(netID, axisID, 5.5, 0, 2, ref errorCode);
    if (errorCode != 0)
    {
        //
    }

    //
    ecmSxCfg_SetZVISEnable(netID, axisID, true, ref errorCode);
    if (errorCode != 0)
    {
        //
    }
}
```

¹⁾ ²⁾

ComiECAT SDK

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