

- Case 1 1
 - AddInfo 1
 - Cause 1
 - Solution 1
 - Config Info 2
- Case 2 2
 - AddInfo 2
 - Cause 2
 - Solution 3
- Case 3 3
 - AddInfo 3
 - Cause 3
 - Solution 3
- Case 4 3
 - AddInfo 3
 - Cause 3
 - Solution 4

, , torque, , ,

× 가

Case 1

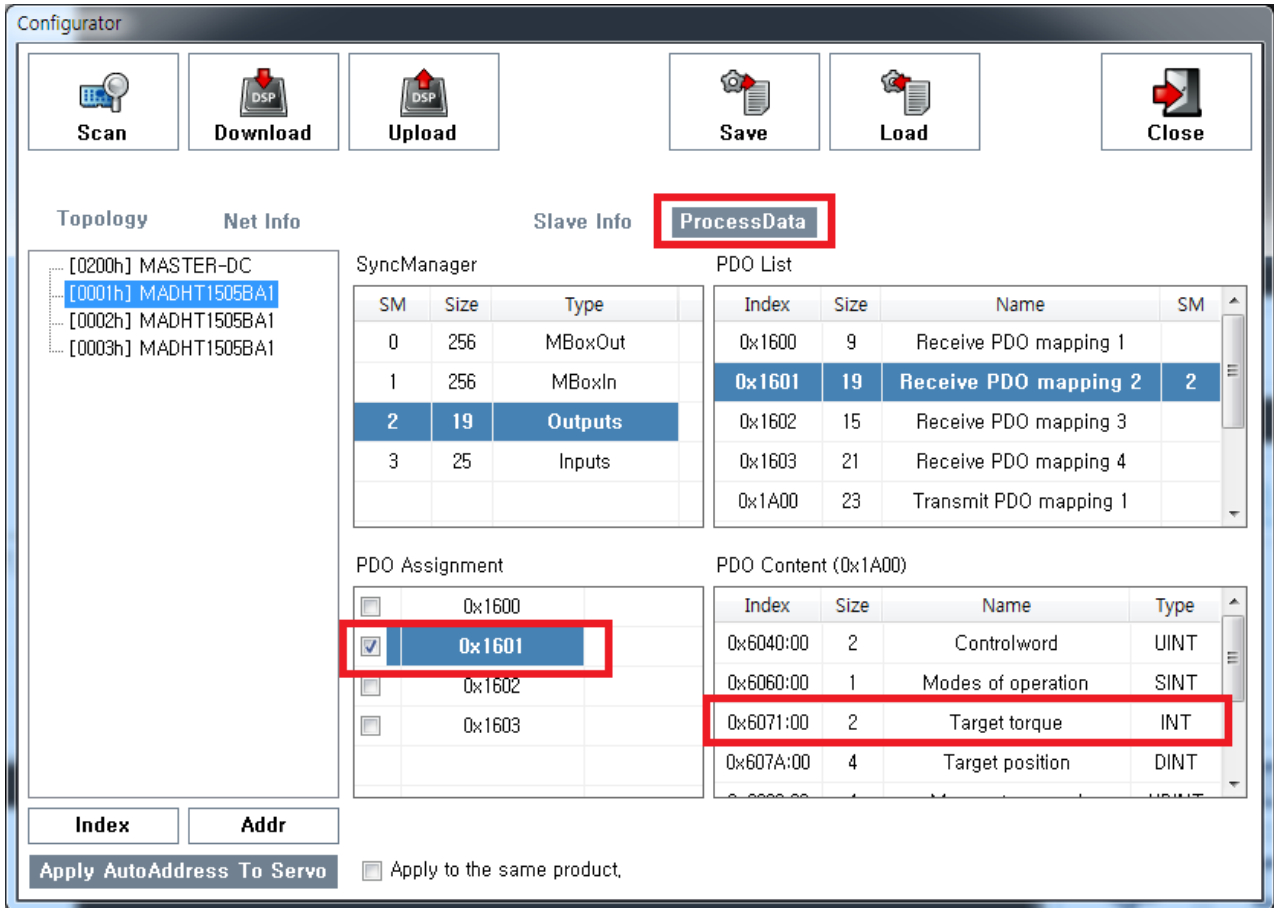
AddInfo
(Cyclic Torque Mode) Target Torque 가 가 .

Cause

- OutPDO Data Torque
- ¹⁾

Solution

- OutPDO Data Torque 가 Configuration
◦ Torque OutPDO Map



- Config

Configuration Guide

- XML

. (OMRON xml)

- Torque Monitor가

Torque Monitor Failed

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Config Info



Case 2

AddInfo

-

Cause

- SDO 0x6080 (Max motor speed) 0 2)

Solution

- SDO 0x6080 (Max motor speed)
- rpm

Case 3

AddInfo

-

Cause

- Pr0.00 0
-
- (Polarity)³⁾ , 0x607E

Solution

- Pr0.00 0

Case 4

AddInfo

-

Cause

- Pr0.08 0
- **PANASONIC :**

Solution

- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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