

.....	1
.....	1
Case 1 .....	1
Case 2 .....	2
Case 3 .....	2
Case 4 .....	2

x 가

(Cyclic Torque Mode) Target Torque 가 가

### Case 1

- OutPDO Data Torque

1)

- OutPDO Data Torque 가 Configuration
  - Torque OutPDO Map

The screenshot shows the 'Configurator' software interface. At the top, there are buttons for Scan, Download, Upload, Save, Load, and Close. Below these are tabs for Topology, Net Info, Slave Info, and ProcessData (which is highlighted with a red box). The ProcessData tab contains several tables:

- SyncManager:** A table with columns SM, Size, and Type. Row 2 is highlighted with a blue background and labeled 'Outputs'.
- PDO List:** A table with columns Index, Size, Name, and SM. Row 2 is highlighted with a blue background and labeled 'Receive PDO mapping 2'.
- PDO Assignment:** A table with columns Index, Size, and Type. Row 2 is highlighted with a blue background and labeled '0x1601'.
- PDO Content (0x1A00):** A table with columns Index, Size, Name, and Type. Row 3 is highlighted with a blue background and labeled 'Target torque'.

At the bottom, there are buttons for 'Index' and 'Addr', and a checkbox for 'Apply AutoAddress To Servo'.

- Config

### Configuration Guide

- XML

. (OMRON xml )

- Torque Monitor가

### Torque Monitor Failed

#### Case 2

- 

- SDO 0x6080 (Max motor speed) 0 <sup>2)</sup>

- SDO 0x6080 (Max motor speed)

- rpm

#### Case 3

- 

- Pr0.00 0

- 

- (Polarity) <sup>3)</sup> , 0x607E

- Pr0.00 0

#### Case 4

-

- Pr0.08 0
- **PANASONIC :**
- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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