

.....	1
.....	1
Case 1 .....	1
Case 2 .....	2
Case 3 .....	2
Case 4 .....	2

x 가 .

(Cyclic Torque Mode)

Target Torque 가 .

가 .

### Case 1

- OutPDO Data Torque

.

1)

- OutPDO Data Torque
  - Torque Configuration

OutPDO Map

SyncManager	PDO List			
SM	Index	Size	Name	SM
0	0x1600	9	Receive PDO mapping 1	
1	0x1602	15	Receive PDO mapping 3	
<b>2</b>	<b>0x1601</b>	<b>19</b>	<b>Receive PDO mapping 2</b>	<b>2</b>
3	0x1603	21	Receive PDO mapping 4	
	0x1A00	23	Transmit PDO mapping 1	

PDO Assignment	PDO Content (0x1A00)
0x1600	Index: 0x6040:00, Size: 2, Name: Controlword, Type: UINT
<b>0x1601</b>	<b>0x6071:00</b> , <b>2</b> , <b>Target torque</b> , <b>INT</b>
0x1602	Index: 0x6060:00, Size: 1, Name: Modes of operation, Type: SINT
0x1603	Index: 0x607A:00, Size: 4, Name: Target position, Type: DINT

Index Addr

Apply AutoAddress To Servo  Apply to the same product.

- Config
- XML
- Torque Monitor가

## Configuration Guide

. (OMRON xml )

## Torque Monitor Failed

### Case 2

- 
- SDO 0x6080 (Max motor speed) 0 <sup>2)</sup>
- SDO 0x6080 (Max motor speed)
- rpm

### Case 3

- 
- Pr0.00 0
- 
- , 0x607E  
(Polarity) <sup>3)</sup>
- Pr0.00 0

### Case 4

-

- Pr0.08 0
- **PANASONIC :**
  
- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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